

Semnan University Faculty of Mechanical Engineering

انسكده مهندسي م

دانشکده مهندسی مکانیک

درس مکاترونیک ۱

MECHATRONICS 1

Section 1:

Introduction to Mechatronics

Reference:

Mechatronics Electronic control systems in mechanical and electrical engineering 6th Edition William Bolton

Chapter 1 - Introducing mechatronics



1.1 What is mechatronics?

- The term mechatronics was 'invented' by a Japanese engineer in 1969, as a combination of 'mecha' from mechanisms and 'tronics' from electronics.
 - □ Integration of mechanical engineering with electronics and intelligent computer control in the design and manufacture of products and processes.
- As a result, mechatronic products have many mechanical functions replaced with electronic ones. This results in much greater flexibility, easy redesign and reprogramming, and the ability to carry out automated data collection and reporting.



1.1 What is mechatronics?

Mechatronics brings together areas of technology involving sensors and measurement systems, drive and actuation systems, and microprocessor systems, together with the analysis of the behavior of systems and control systems.



1.2 The design process

- □ The design process:
 - 1) The need
 - 2) Analysis of the problem
 - 3) Preparation of a specification
 - 4) Generation of possible solution
 - 5) Selections of a suitable solution
 - 6) Production of a detailed design
 - 7) Production of working drawings



1.3 Systems

□ In designing mechatronic systems, one of the steps involved is the creation of a model of the system so that predictions can be made regarding its behavior when inputs occur.



1.2 The design process

- The term modelling is used when we represent the behavior of a real system by mathematical equations, such equations representing the relationship between the inputs and outputs from the system.
- □ The response of any system to an input is not instantaneous.
 - Spring System

 Input:
 force at
 time 0

 Spring
 Output:
 extension
 which changes
 with time

 Time

 Time

 Time

 Time

 7



1.4 Measurement systems

- Measurement systems can, in general, be considered to be made up of three basic elements:
 - 1) A sensor
 - 2) A signal conditioner
 - 3) A display system



1.4 **Measurement** systems A digital thermometer system Signal in suitable Value Quantity Signal related form for of the being to quantity display: quantity measured: measured: Display Sensor Amplifier temperature potential bigger difference voltage



□ A control system can be thought of as a system which can be used to:

- 1) Control some variable to some particular value
- 2) Control the sequence of events
- 3) Control whether an event occurs or not
- □ Feedback control:
 - Signals are fed back from the output, in order to modify the reaction of the body to enable it to restore to the 'normal' value.





Control systems 1.5 Open- and closed-loop systems Heating a room Output: Input: Controller, Electric Switch i.e. person fire decision to Hand Electric a temperature switch on activated change power or off Comparison element Input: Output: Controller, Electric Switch i.e. person fire required Deviation Hand Electric a constant temperature signal activated power temperature Measuring device Feedback of temperature-related signal



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□ Basic elements of a closed-loop system

- 1) Comparison element
- 2) Control element
- 3) Correction element
- 4) Process element
- 5) Measurement element





□ The automatic control of water level



Section 1 - Introduction

1.5 Control systems

□ Shaft speed control



Section 1 - Introduction

1.5 Control systems

□ Shaft speed control



- Analogue and digital control systems
 - Analogue systems are ones where all the signals are continuous functions of time and it is the size of the signal which is a measure of the variable.
 - Digital signals can be considered to be a sequence of on/off signals, the value of the variable being represented by the sequence of on/off pulses



Digital closed-loop control system





Microcontroller control





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□ Washing machine

Inputs





Feedback from outputs of water level, water temperature, drum speed and door closed

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